

# Mathematical Economics: Lecture 16

Yu Ren

WISE, Xiamen University

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# Outline

- 1 Chapter 21: Concave and Quasiconcave Functions

# New Section

# Chapter 21: Concave and Quasiconcave Functions

# Concave and convex functions

## Definition

- A real-valued function  $f$  defined on a convex subset  $U$  of  $R^n$  is **concave** if for all  $X, Y$  in  $U$  and for all  $t$  between 0 and 1,  $f(tX + (1 - t)Y) \geq tf(X) + (1 - t)f(Y)$ .

Figure 21.2

- A real-valued function  $f$  defined on a convex subset  $U$  of  $R^n$  is **convex** if for all  $X, Y$  in  $U$  and for all  $t$  between 0 and 1,  $f(tX + (1 - t)Y) \leq tf(X) + (1 - t)f(Y)$ .

Figure 21.3

# Concave and convex functions

$f$  is concave if and only if  $-f$  is convex

# Concave and convex functions

Different with **convex set**: whenever  $X$  and  $Y$  are points in  $U$ , the line segment joining  $X$  to  $Y$   $I(X, Y) \equiv \{tX + (1 - t)Y : 0 \leq t \leq 1\}$  is also in  $U$ . Figure 21.1

# Concave and convex functions

A function  $f$  of  $n$  variables is **concave** if and only if any secant line connecting two points on the graph of  $f$  lies **below** the graph. A function  $f$  of  $n$  variables is **convex** if and only if any secant line connecting two points on the graph of  $f$  lies **above** the graph.

# Concave and convex functions

**Theorem 21.1** Let  $f$  be a function defined on a convex subset  $U$  of  $R^n$ . Then,  $f$  is concave (convex) if and only if its restriction to every line segment in  $U$  is a concave (convex) function of one variable.



# Concave and convex functions

Calculus Criteria for Concavity:

**Theorem 21.2** Let  $f$  be a  $C^1$  function on an interval  $I$  in  $R$ . Then,  $f$  is concave on  $I$  if and only if  $f(y) - f(x) \leq f'(x)(y - x)$  for all  $x, y \in I$ . The function  $f$  is convex on  $I$  if and only if  $f(y) - f(x) \geq f'(x)(y - x)$  for all  $x, y \in I$ .

# Concave and convex functions

**Theorem 21.3** let  $f$  be a  $C^1$  function on a convex subset  $U$  of  $R^n$ . Then,  $f$  is concave on  $U$  if and only if for all  $X, Y$  in  $U$ :

$f(Y) - f(X) \leq Df(X)(Y - X)$ . Similarly,  $f$  is convex on  $U$  if and only if for all  $X, Y$  in  $U$ :

$f(Y) - f(X) \geq Df(X)(Y - X)$  for all  $X, Y$  in  $U$ .

# Concave and convex functions

**Corollary 21.4** If  $f$  is a  $C^1$  concave function on a convex set  $U$  and if  $X_0 \in U$ , then  $Df(X_0)(Y - X_0) \leq 0$  implies  $f(Y) \leq f(X_0)$ . In particular, if  $Df(X_0)(Y - X_0) \leq 0$  for all  $Y \in U$ , then  $X_0$  is a global max of  $f$ .

# Concave and convex functions

**Theorem 21.5** Let  $f$  be a  $C^2$  function on an open convex subset  $U$  of  $R^n$ . Then,  $f$  is a concave function on  $U$  if and only if the Hessian  $D^2f(X)$  is negative semidefinite for all  $X$  in  $U$ . The function  $f$  is a convex function on  $U$  if and only if  $D^2f(X)$  is positive semidefinite for all  $X$  in  $U$ .

# Example 21.1

**Example 21.1** Let us apply the test of Theorem 21.3 to show that  $f(x_1, x_2) = x_1^2 + x_2^2$  is convex on  $R^n$ . The function  $f$  is convex if and only if

$$\begin{aligned} (y_1^2 + y_2^2) - (x_1^2 + x_2^2) &\geq (2x_1 \ 2x_2) \begin{pmatrix} y_1 - x_1 \\ y_2 - x_2 \end{pmatrix} \\ &= 2x_1y_1 - 2x_1^2 + 2x_2y_2 - 2x_2^2 \end{aligned}$$

# Example 21.1

if and only if

$$y_1^2 + y_2^2 + x_1^2 + x_2^2 - 2x_1y_1 - 2x_2y_2 \geq 0$$

if and only if

$$(y_1 - x_1)^2 + (y_2 - x_2)^2 \geq 0$$

which is true for all  $(x_1, x_2)$  and  $(y_1, y_2)$  in  $R^2$ .

# Example 21.2

**Example 21.2** The Hessian of the function  $f(x, y) = x^4 + x^2y^2 + y^4 - 3x - 8y$  is

$$D^2f(x, y) = \begin{pmatrix} 12x^2 + 2y^2 & 4xy \\ 4xy & 12x^2 + 2y^2 \end{pmatrix}$$

For  $(x, y) \neq (0, 0)$ , the two leading principal minors,  $12x^2 + 2y^2$  and  $24x^4 + 132x^2y^2 + 24y^4$ , are both positive, so  $f$  is a convex function on all  $R^n$ .

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# Example 21.3

**Example 21.3** A commonly used simple utility or production function is  $F(x, y) = xy$ . Its Hessian is

$$D^2F(x, y) = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$$

whose second order principal minor is  $\det D^2F(x, y) = -1$ . Since this second principal minor is negative,  $D^2F$  is indefinite and  $F$  is neither concave nor convex.

# Example 21.4

**Example 21.4** Consider the monotonic transformation of the function  $F$  in the previous example by the function  $g(z) = z^{1/4} : G(x, y) = x^{1/4}y^{1/4}$ , defined only on the positive quadrant  $R_+^2$ . The Hessian of  $G$  is

$$D^2G(x, y) = \begin{pmatrix} -\frac{3}{16}x^{-7/4}y^{1/4} & \frac{1}{16}x^{3/4}y^{-3/4} \\ \frac{1}{16}x^{-3/4}y^{-3/4} & -\frac{3}{16}x^{1/4}y^{-7/4} \end{pmatrix}$$

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# Example 21.4

For  $x > 0, y > 0$ , the first order leading principal minor is negative and the second order leading principal minor,  $x^{-3/2}y^{-3/2}/128$ , is positive. Therefore,  $D^2G(x, y)$  is negative definite on  $R_+^2$  and  $G$  is a concave function on  $R_+^2$ .

# Example 21.5

**Example 21.5** Now, consider the general Cobb-Douglas function on  $R_+^2$  :  $U(x, y) = x^a y^b$ . Its Hessian is

$$D^2U(x, y) = \begin{pmatrix} a(a-1)x^{a-2}y^b & abx^{a-1}y^{b-1} \\ abx^{a-1}y^{b-1} & b(b-1)x^a y^{b-2} \end{pmatrix}$$

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# Example 21.5

whose determinant is

$$\det D^2 U(x, y) = ab(1 - a - b)x^{2a-2}y^{2b-2}.$$

In order for  $U$  to be concave on  $R_+^2$ , we need  $a(a - 1) < 0$  and  $ab(1 - a - b) > 0$ ; that is, we need  $0 < a < 1$ ,  $0 < b < 1$ , and  $a + b \leq 1$ . In summary, a Cobb-Douglas production function on  $R_+^2$  is concave if and only if it exhibits constant or decreasing returns to scale.



# Properties of Concave functions

**Theorem 21.6** Let  $f$  be a concave (convex) function on an open convex subset  $U$  of  $R^n$ . If  $x_0$  is a critical point of  $f$ , that is,  $Df(x_0) = 0$ , then  $x_0 \in U$  is a global maximizer (minimizer) of  $f$  on  $U$ .

# Properties of Concave functions

**Theorem 21.7** Let  $f$  be a  $C^1$  function defined on a convex subset  $U$  of  $R^n$ . If  $f$  is a concave function and if  $x_0$  is a point in  $U$  which satisfies  $Df(x_0)(y - x_0) \leq 0$  for all  $y \in U$ , then  $x_0$  is a global maximizer of  $f$  on  $U$ .

# Example 21.6

**Example 21.6** If  $f$  is a  $C^1$  increasing, concave function of one variable on the interval  $[a,b]$ , then  $f'(b)(x - b) \leq 0$  for all  $x \in [a, b]$ . By Theorem 21.7,  $b$  is the global maximizer of  $f$  on  $[a,b]$ .

# Example 21.7

**Example 21.7** Consider the concave function  $U(x, y) = x^{1/4}y^{1/4}$  on the (concave) triangle

$$B = \{(x, y) : x \geq 0, y \geq 0, x + y \leq 2\}.$$

By symmetry, we would expect that  $(x_0, y_0) = (1, 1)$  is the maximizer of  $U$  on  $B$ . To prove this, use Theorem 21.7. Let  $(x, y)$  be an arbitrary point in  $B$ .

# Example 21.7

$$\begin{aligned}\frac{\partial U}{\partial x}(1, 1)(x - 1) + \frac{\partial U}{\partial y}(1, 1)(y - 1) \\ &= \frac{1}{4}(x - 1) + \frac{1}{4}(y - 1) \\ &= \frac{1}{4}(x + y - 2) \\ &\leq 0\end{aligned}$$

since  $x + y - 2 \leq 0$  for  $(x, y)$  in the constraint set  $B$ . By Theorem 21.7,  $(1, 1)$  is the global maximizer of  $U$  on  $B$ .

# Example 21.8

**Example 21.8** Consider the problem of maximizing profit for a firm whose production function is  $y = g(x)$ , where  $y$  denotes output and  $x$  denotes the input bundle. If  $p$  denotes the price of the output and  $w_i$  is the cost per unit of input  $i$ , then the firm's profit function is

$$\Pi(x) = pg(x) - (w_1x_1 + \cdots + w_nx_n)$$

# Example 21.8

As can easily be checked,  $\Pi$  will be a concave function provided that the production function is a concave function. In this case, the first order condition

$$p \frac{\partial g}{\partial x_i} = w_i \text{ for } i = 1, 2, \dots, n,$$

which says marginal revenue product equals the factor price for each point, is both necessary and sufficient for an interior profit maximizer.

# Example 21.8

If one wants to study the effect of changes in  $w_i$  or  $p$  on the optimal input bundle, one would apply the comparative statics analysis to system. Since profit is concave for all  $p$  and  $w$ , the solution to system will automatically be the optimal input for all choices of  $p$  and  $w$ .



# Properties of Concave functions

**Theorem 21.8** Let  $f_1, \dots, f_k$  be concave (convex) functions. each defined on the same convex subset  $U$  of  $R^n$ . Let  $a_1, \dots, a_k$  be positive numbers. Then,  $a_1 f_1 + \dots + a_k f_k$  is a concave (convex) function on  $U$ .

# Properties of Concave functions

**Theorem 21.9** let  $f$  be a function defined on a convex set  $U$  in  $R^n$ . If  $f$  is concave, then for every  $x_0$  in  $U$ , the set

$C_{x_0}^+ \equiv \{x \in U : f(x) \geq f(x_0)\}$  is a convex set. If  $f$  is convex, then for every  $x_0$  in  $U$ , the set

$C_{x_0}^- \equiv \{x \in U : f(x) \leq f(x_0)\}$  is a convex set.

# Quasiconcave and Quasiconvex

- Definition: a function  $f$  defined on a convex subset  $U$  of  $R^n$  is quasiconcave if for every real number  $a$ ,  $C_a^+ \equiv \{x \in U : f(x) \geq a\}$  is a convex set. Similarly,  $f$  is quasiconvex if for every real number  $a$ ,  $C_a^- \equiv \{x \in U : f(x) \leq f(x_0)\}$  is a convex set.
- Figure 21.9

# Quasiconcave and Quasiconvex

**Theorem 21.12** Let  $f$  be a function defined on a convex set  $U$  in  $R^n$ . Then, the following statements are equivalent to each other:

- (a)  $f$  is a quasiconcave function on  $U$
- (b) For all  $X, Y \in U$  and all  $t \in [0, 1]$   $f(X) \geq f(Y)$  implies  $f(tX + (1 - t)Y) \geq f(Y)$
- (c) For all  $X, Y \in U$  and all  $t \in [0, 1]$   $f(tX + (1 - t)Y) \geq \min\{f(Y), f(X)\}$ .

# Example 21.9

**Example 21.9** Consider the Leontief or fixed-coefficient production function  $Q(x, y) = \min\{ax, by\}$  with  $a, b > 0$ . The level sets of  $Q$  are drawn in Figure 21.7. Certainly, the region above and to the right of any of this function's L-shaped level sets is a convex set.  $Q$  is quasiconcave.

# Extra Theorem

**Theorem 21.\*** Any monotonic transformation of a concave function is quasiconcave.

# Quasiconcave and Quasiconvex

**Theorem 21.13** Every Cobb-Douglas function  $F(x, y) = Ax^a y^b$  with  $A$ ,  $a$  and  $b$  all positive is quasiconcave.

# Example 21.10

**Example 21.10** Consider the constant elasticity of substitution (CES) production function

$$Q(x, y) = (a_1 x_1^r + a_2 x_2^r)^{1/r}, \text{ where } 0 < r < 1.$$

By Theorem 21.8 and Exercise 21.4,  $(a_1 x_1^r + a_2 x_2^r)$  is concave. Since  $g(z) = z^{1/r}$  is a monotonic transformation,  $Q$  is a monotonic transformation of a concave function and therefore is quasiconcave.



# Example 21.11

**Example 21.11** Let  $y = f(x)$  be any increasing function on  $R^1$ , as in Figure 21.8. For any  $x^*$ ,  $\{x : f(x) \geq f(x^*)\}$  is just the interval  $[x^*, \infty)$ , a convex subset of  $R^1$ . So,  $f$  is quasiconcave. On the other hand,  $\{x : f(x) \leq f(x^*)\}$  is the concave set  $(-\infty, x^*]$ . Therefore, an increasing function on  $R^1$  is both quasiconcave and quasiconvex. The same argument applies to decreasing function.

# Example 21.12

**Example 21.12** Any function on  $R^1$  which rises monotonically until it reaches a global maximum and then monotonically falls, such as  $y = -x^2$  or the bell-shaped probability density function  $y = ke^{-x^2}$ , is a quasiconcave function, as Figure 21.9 indicates. For any  $x_1$  as in Figure 21.9, there is a  $x_2$  such that  $f(x_1) = f(x_2)$ . Then,  $\{x : f(x) \geq f(x_1)\}$  is the convex interval  $[x_1, x_2]$ .

# Quasiconcave and quasiconvex

Calculus Criteria: **Theorem 21.14** Suppose that  $F$  is a  $C^1$  function on an open convex subset  $U$  of  $R^n$ . Then,  $F$  is quasiconcave on  $U$  if and only if  $F(y) \geq F(x)$  implies that  $DF(x)(y - x) \geq 0$ ;  $F$  is quasiconvex on  $U$  if and only if  $F(y) \leq F(x)$  implies that  $DF(x)(y - x) \leq 0$ ;

# Quasiconcave and quasiconvex

**Theorem 21.15** Suppose that  $F$  is a real-valued positive function defined on a convex cone  $C$  in  $R^n$ . If  $F$  is homogeneous of degree one and quasiconcave on  $C$ , it is concave on  $C$ .

# Pseudoconcave and Pseudoconvex

Definition : Let  $U$  be an open convex subset of  $R^n$ . A  $C^1$  function  $F : U \rightarrow R$  is pseudoconcave at  $x^* \in U$  if  $DF(x^*)(y - x^*) \leq 0$  implies  $F(y) \leq F(x^*)$  for all  $y \in U$ . The function  $F$  is pseudoconcave on  $U$  if (15) holds for all  $x^* \in U$ . To define a pseudoconvex function on  $U$ , one simply reverses **all** inequalities.

# Pseudoconcave and Pseudoconvex

**Theorem 21.16** Let  $U$  be a convex subset of  $R^n$ , and let  $F : U \rightarrow R$  be a  $C^1$  pseudoconcave function. If  $x^* \in U$  has the property  $DF(x^*)(y - x^*) \leq 0$  for all  $y \in U$ , for example,  $DF(x^*) = 0$ , then  $x^*$  is a global max of  $F$  on  $U$ . An analogous result holds for pseudoconvex functions.

# Pseudoconcave and Pseudoconvex

**Theorem 21.17** Let  $U$  be a convex subset of  $R^n$ . Let  $F : U \rightarrow R$  be a  $C^1$  function. Then, (a) if  $F$  is pseudoconcave on  $U$ ,  $F$  is quasiconcave on  $U$ , and (b) if  $U$  is open and if  $\nabla F(x) \neq 0$  for all  $x \in U$ , then  $F$  is pseudoconcave on  $U$  if and only if  $F$  is quasiconcave on  $U$ .

# Pseudoconcave and Pseudoconvex

**Theorem 21.18** Let  $U$  be an open convex subset of  $R^n$ . Let  $F : U \rightarrow R$  be a  $C^1$  function on  $U$ . Then,  $F$  is pseudoconcave on  $U$  if and only if for each  $x^*$  in  $U$ ,  $x^*$  is the solution to the constrained maximization problem  $\max F(x)$  s.t  $C_{x^*} \equiv \{y \in U : DF(x^*)(y - x^*) \leq 0\}$ .



# Pseudoconcave and Pseudoconvex

**Theorem 21.19** Let  $F$  be a  $C^2$  function on an open convex subset  $W$  in  $R^n$ . Consider the bordered Hessian  $H$  (a) If the largest  $(n-1)$  leading principal minors of  $H$  alternate in sign, for all  $x \in W$ , with the smallest of these positive, then  $F$  is pseudoconcave, and therefore quasiconcave, on  $W$ . (b) If these largest  $(n-1)$  leading principal minors are all negative for all  $x \in W$ , then  $F$  is pseudoconvex, and therefore quasiconvex, on  $W$ .

# Pseudoconcave and Pseudoconvex

**Theorem 21.20** Let  $F$  be a  $C^2$  function on a convex set  $W$  in  $R^2$ . Suppose that  $F$  is monotone in that  $F'_x > 0$  and  $F'_y > 0$  on  $W$ . If the determinant (18) is positive for all  $(x, y) \in W$ , then  $F$  is quasiconcave on  $W$ . If the determinant (19) is negative for all  $(x, y) \in W$ , then  $F$  is quasiconvex on  $W$ . Conversely, if  $F$  is quasiconcave on  $W$ , then the determinant (19) is positive; if  $F$  is quasiconvex on  $W$ , then the determinant (19) is  $\leq 0$  for all  $(x, y) \in W$ .

# Example 21.13

**Example 21.13** Theorem 21.13 implies that the Cobb-Douglas function  $U(x, y) = x^a y^b$  is quasiconcave on  $R_+^2$  for  $a, b > 0$  since it is a monotone transformation of a concave function. Let's use Theorem 21.20 to prove the quasiconcavity of  $U$ . The bordered Hessian is

$$\begin{pmatrix} 0 & ax^{a-1}y^b & bx^ay^{b-1} \\ ax^{a-1}y^b & a(a-1)x^{a-1}y^b & abx^{a-1}y^{b-1} \\ bx^ay^{b-1} & abx^{a-1}y^{b-1} & b(b-1)x^ay^{b-2} \end{pmatrix}$$

# Example 21.13

whose determinant is

$$(ab + ab^2 + a^2b)x^{3a-2}y^{3b-2},$$

which is always positive for  $x > 0, y > 0, a > 0, b > 0$ . By Theorem 21.20,  $U$  is pseudoconcave, and therefore quasiconcave.

# Concave Programming

Unconstrained Problems : **Theorem 21.21** Let  $U$  be a convex subset of  $R^n$ . Let  $f : U \rightarrow R$  be a  $C^1$  concave (convex) function on  $U$ . Then,  $x^*$  is a global max of  $f$  on  $U$  if and only if

$Df(x^*)(x - x^*) \leq 0$  for all  $x \in U$ . In particular, if  $U$  is open, or if  $x^*$  is an interior point of  $U$ , then  $x^*$  is a global max(min) of  $f$  on  $U$  if and only if  $Df(x^*) = 0$

# Concave Programming

Constrained Problem : **Theorem 21.22** Let  $U$  be a convex open subset of  $R^n$ . Let  $f : U \rightarrow R$  be a  $C^1$  pseudoconcave function on  $U$ . Let  $g_1, \dots, g_k : U \rightarrow R$  be  $C^1$  quasiconvex functions. If  $(x^*, \lambda^*)$  satisfy the Lagrangian conditions,  $x^*$  is a global max of  $f$  on the constraint set.

# Concave Programming

**Theorem 21.23** let  $f, g_1, \dots, g_k$  be as in the hypothesis of Theorem 21.22. (a) For any fixed  $b = (b_1, \dots, b_k) \in R^k$ , let  $Z(b)$  denote the set of  $x \in C_b$  that are global maximizers of  $f$  on  $C_b$ . Then,  $Z(b)$  is a convex set. (b) For any  $b \in R^k$ , let  $V(b)$  denote the maximal value of the objective function  $f$  in problem (20). If  $f$  is concave and the  $g_i$  are convex, then  $b \rightarrow V(b)$  is a concave function of  $b$ .

# Concave Programming

Saddle Point: Definition: Let  $U$  be a convex subset of  $R^n$ . Consider the Lagrangian function (21) for the programming problem (20), as a function of  $x$  and  $\lambda$ . Then,  $(x^*, \lambda)$  is saddle point of  $L$  if  $L(x, \lambda^*) \leq L(x^*, \lambda^*) \leq L(x^*, \lambda)$  for all  $\lambda \geq 0$  and all  $x \in U$ . Usually,  $U = R^n$  or  $U = R_+^n$ , the positive orthant of  $R^n$ . In the latter case, we say that  $(x^*, \lambda^*)$  is a nonnegative saddle point of  $L$



# Concave Programming

**Theorem 21.24** If  $(x^*, \lambda^*)$  is a (nonnegative) saddle point for  $L$  in Problem (20), then  $x^*$  maximizes  $f$  on  $C_b(C_b \cap R_+^n)$ .

# Concave Programming

**Theorem 21.25** Suppose that  $U = R_+^n$  or that  $U$  is an open convex subset of  $R^n$ . Suppose that  $f$  is a  $C^1$  concave function and that  $g_1, \dots, g_k$  are  $C^1$  convex functions on  $U$ . Suppose that  $x^*$  maximizes  $f$  on the constraint set  $C_b$  as defined in (20). Suppose further that one of the constraint qualifications in Theorem 19.12 holds. Then, there exists  $\lambda^* > 0$  such that  $(X^*, \lambda^*)$  is a saddle point of the Lagrangian (21)